



# Hash-Based Indexes

## Chapter 11





# Introduction

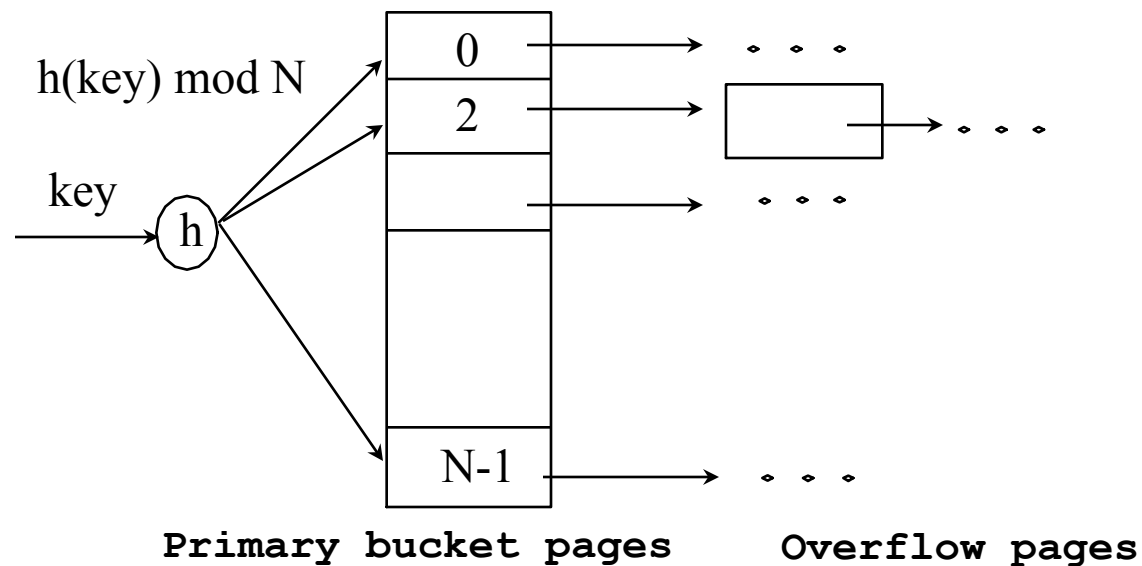
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- ❖ *Hashing maps a search key directly to the pid of the containing page/page-overflow chain*
- ❖ *Doesn't require intermediate page fetches for internal "steering nodes" of tree-based indices*
- ❖ *Hash-based indexes are best for *equality selections*. They do not support efficient range searches.*
- ❖ *Static and dynamic hashing techniques exist with trade-offs similar to ISAM vs. B+ trees.*



# Static Hashing

- ❖ # primary pages fixed, allocated sequentially, never de-allocated; overflow pages if needed.
- ❖  $h(k) \bmod M =$  bucket to which data entry with key  $k$  belongs. ( $M = \#$  of buckets)





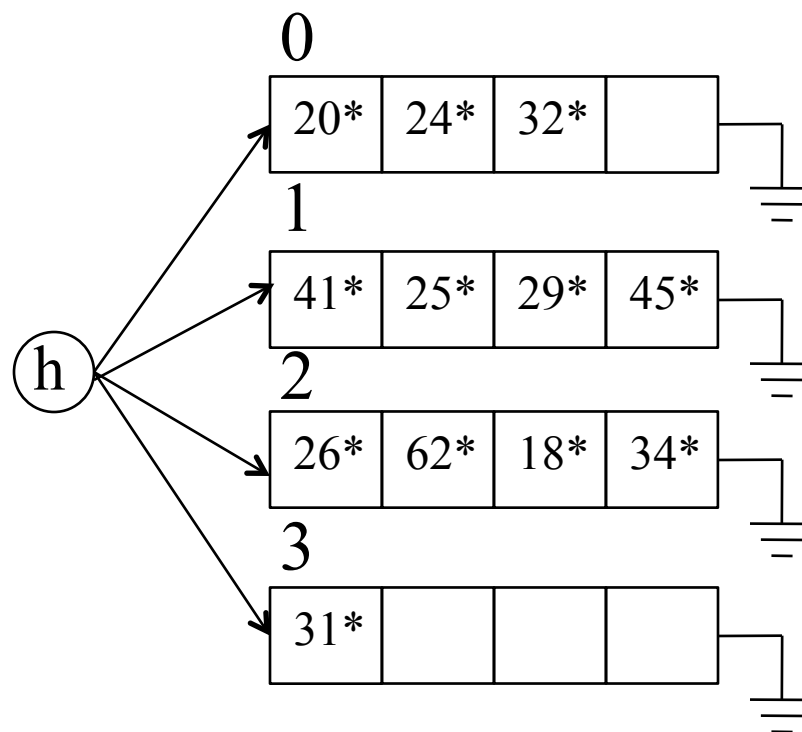
## *Static Hashing (Contd.)*

- ❖ Buckets contain *data entries*.
- ❖ Hash function maps a *search key* to a bin number  $h(key) \rightarrow 0 \dots M-1$ . *Ideally uniformly*.
  - $h(key) = (a * key + b) \bmod M$ , usually works well.
  - a and b are constants; lots known about how to tune **h**.
- ❖ **Long overflow chains** can develop and degrade performance. Dynamic techniques (*Extendible* and *Linear Hashing*) address this problem.



# Static Hashing Example

- ❖ Initially built over “Ages” attribute, with 4 records/page and  $h(\text{Age}) = \text{Age} \bmod 4$



Initial Index

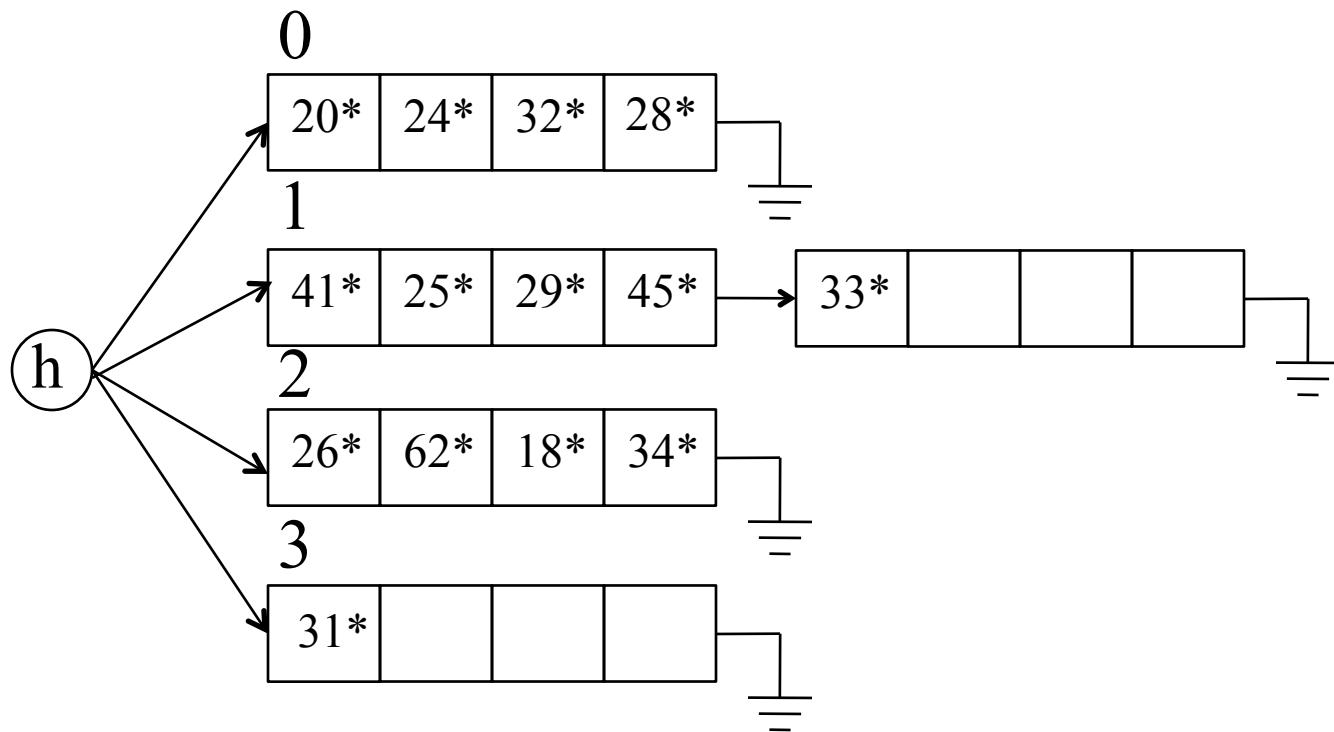
Note: records need  
not be ordered

Average Occupancy?



# Static Hashing Example

- ❖ Adding 28, 33
- ❖ Deleting 31, (leads to empty page)





# *Hashing's "Achilles Heel"*

## ❖ Maintaining Balance

- Data is often "clustered"
- Hash function should uniformly distribute keys over buckets. Demands a good hash function (lots of research in this area)

## ❖ Bucket Spills

- What if M buckets are not enough?  
Solution: new hash function
- Families of hash functions  
 $h_0(\text{key}), h_1(\text{key}), \dots, h_n(\text{key})$
- Transitions only redistribute overflowed buckets



# *Extendible Hashing*

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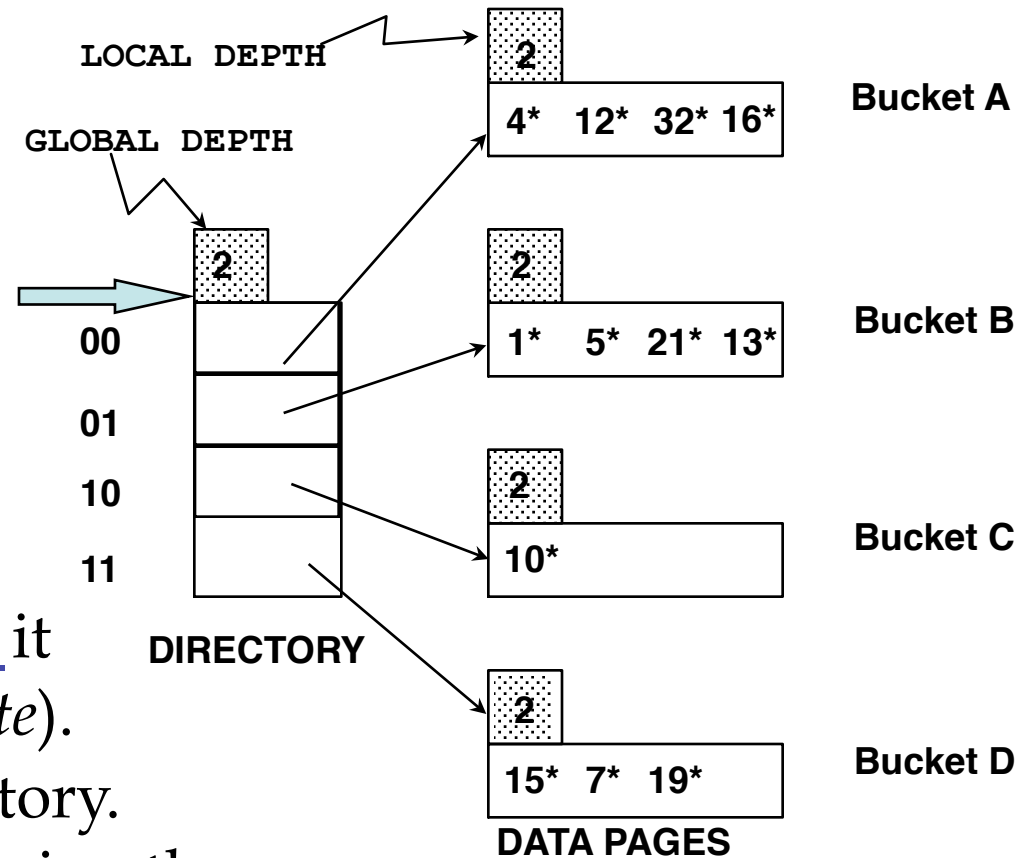
- ❖ Situation: Bucket (primary page) becomes full. Change hashing function and reorganize. Why not reorganize file by *doubling* # of buckets?
  - Reading and writing all pages is expensive!
- ❖ Key Idea: Use *directory of pointers to buckets*, double # of buckets by *doubling the directory*, splitting just the bucket that overflowed!
  - Directory much smaller than file, so doubling it is much cheaper. Only spilt pages are split. *No overflows!*
  - Trick lies in how hash function is adjusted!





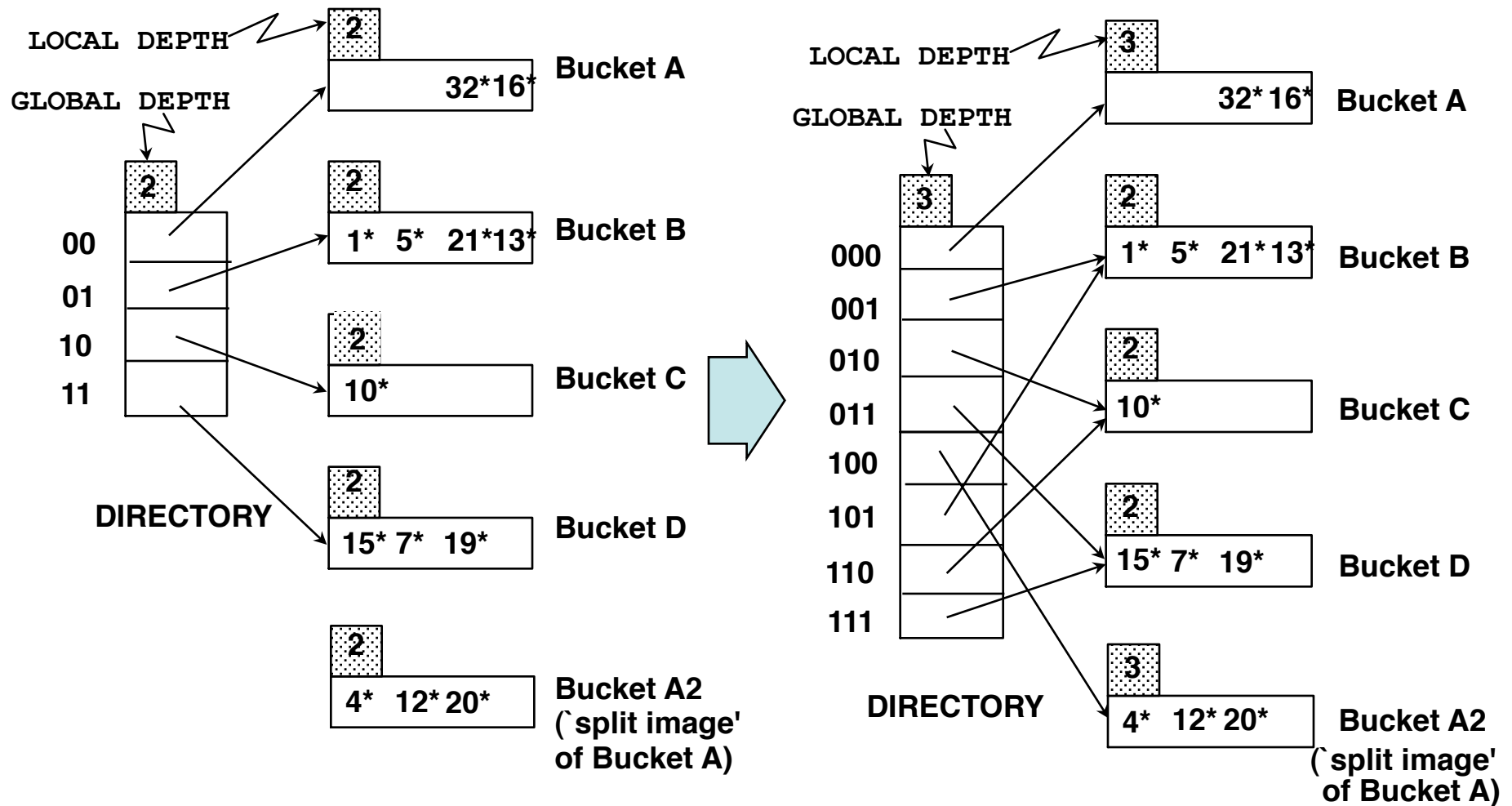
# Example

- ❖ Directory is array of size 4.
- ❖ To find bucket for  $r$ , take last '*global depth*' # bits of  $\mathbf{h}(r)$ ; we denote  $r$  by  $\mathbf{h}(r)$ .
  - If  $\mathbf{h}(r) = 5 = \text{binary } 101$ , it is in bucket pointed to by 01.
- ❖ **Insert:** If bucket is full, *split* it (allocate new page, re-distribute).
- ❖ If necessary, double the directory. (Decision is based on comparing the directory's *global depth* with *local depth* of the bucket.)





# Insert $h(r)=20$ (Causes Doubling)





## *Points to Note*

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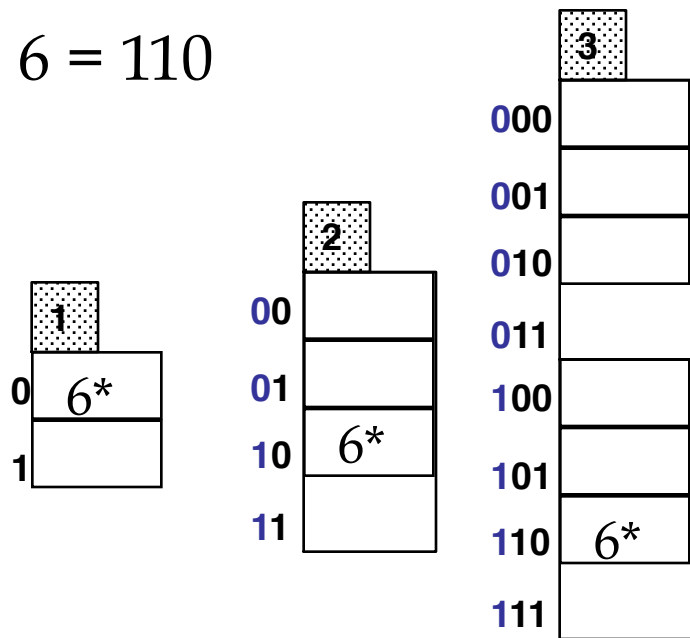
- ❖ 20 = binary 10100. Last **2** bits (00) tell us  $r$  belongs in A or A2. Last **3** bits needed to tell which.
  - *Global depth of directory*: Max # of bits needed to tell which bucket an entry belongs to.
  - *Local depth of a bucket*: # of bits used to determine if an entry belongs to this bucket.
- ❖ When does bucket split cause directory doubling?
  - Before insert, *local depth* of bucket = *global depth*. Insert causes *local depth* to become  $>$  *global depth*; directory is doubled by *copying it over* and 'fixing' pointer to split image page. (Use of least significant bits enables efficient doubling via copying of directory!)



# Directory Doubling

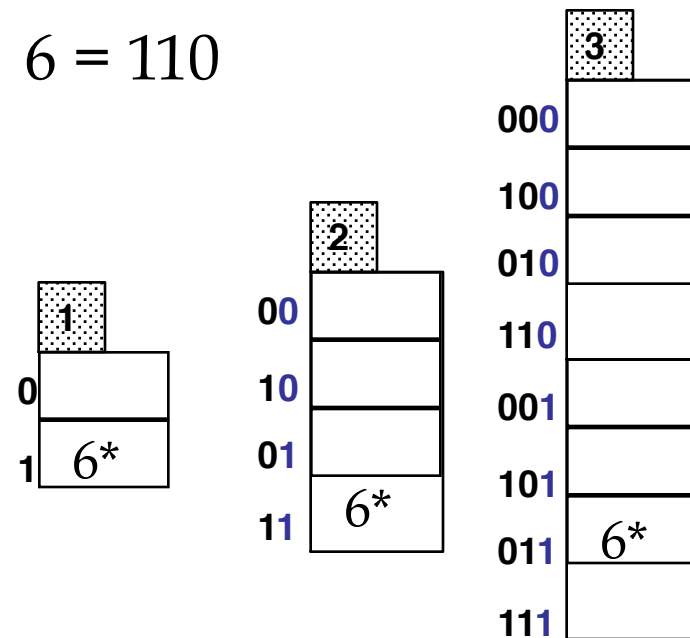
Why use least significant bits in directory?  
 ↳ Allows for doubling via copying!

6 = 110



Least Significant

6 = 110



Most Significant

vs.



# Comments on Extendible Hashing

- ❖ If directory fits in memory, equality search answered with one disk access; else two.
  - 100MB file, 100 bytes/rec, 4K pages contains 1,000,000 records (as data entries) and 25,000 directory elements; chances are high that directory will fit in memory.
  - Directory grows in spurts, and, if the distribution of *hash values* is skewed, directory can grow large.
  - Multiple entries with same hash value cause problems!
- ❖ **Delete:** If removal of data entry makes bucket empty, it can be merged with its 'split image'. If each directory element points to same bucket as its split image, can halve directory.



# Linear Hashing

- ❖ This is another dynamic hashing scheme, an alternative to Extendible Hashing.
- ❖ LH avoids the need for a directory, yet handles the problem of long overflow chains.
- ❖ Idea: Use a family of hash functions  $\mathbf{h}_0, \mathbf{h}_1, \mathbf{h}_2, \dots$ 
  - $\mathbf{h}_i(\text{key}) = \mathbf{h}(\text{key}) \bmod(2^i N)$ ;  $N$  = initial # buckets
  - $\mathbf{h}$  is some hash function (range is *not* 0 to  $N-1$ )
  - If  $N = 2^{d_0}$ , for some  $d_0$ ,  $\mathbf{h}_i$  consists of applying  $\mathbf{h}$  and looking at the last  $d_i$  bits, where  $d_i = d_0 + i$ .
  - $\mathbf{h}_{i+1}$  doubles the range of  $\mathbf{h}_i$  (similar to directory doubling)



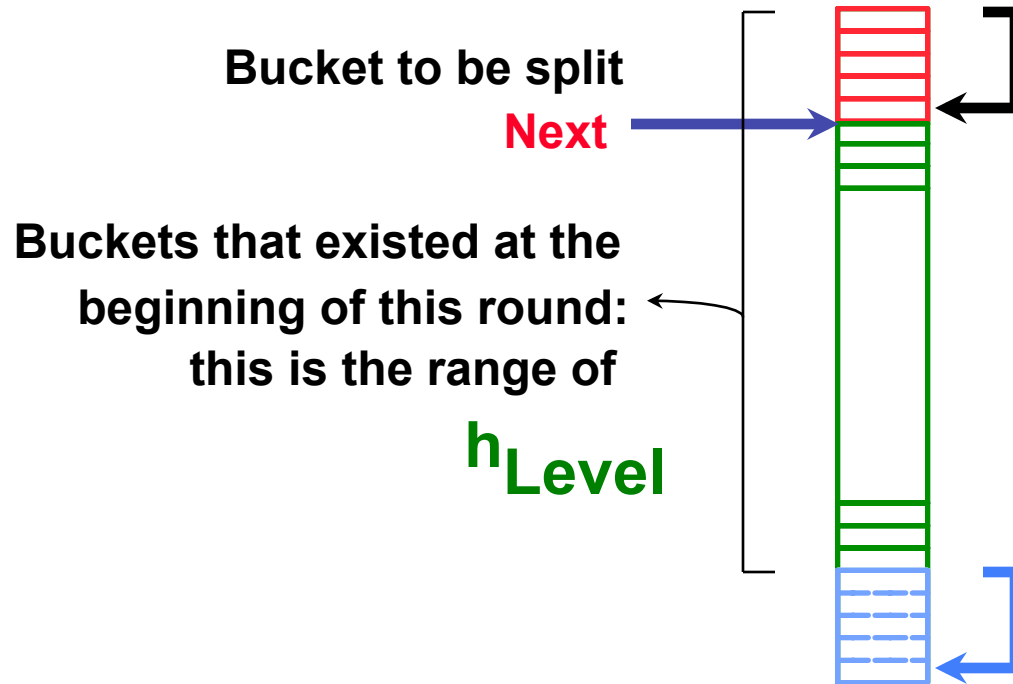
## Linear Hashing (Contd.)

- ❖ Directory avoided in LH by *allowing overflow pages*, and choosing bucket to split *round-robin*.
  - **Splitting proceeds in `rounds`**. Round ends when all  $N_R$  initial (for round  $R$ ) buckets are split. Buckets 0 to **Next-1** have been split; **Next** to  $N_R$  yet to be split.
  - **Current round number is Level**.
  - **Search:** To find bucket for data entry  $r$ , find  $\mathbf{h}_{Level}(r)$ :
    - If  $\mathbf{h}_{Level}(r)$  in range **Next** to  $N_R$ ,  $r$  belongs here.
    - Else,  $r$  could belong to bucket  $\mathbf{h}_{Level}(r)$  or bucket  $\mathbf{h}_{Level}(r) + N_R$ ; must apply  $\mathbf{h}_{Level+1}(r)$  to find out.



# Overview of LH File

- ❖ In the middle of a round.



**Buckets split in this round:**  
If  $h_{Level}$  (search key value) is in this range, must use  $h_{Level-1}$  (search key value) to decide if entry is in 'split image' bucket.

'split image' buckets:  
created (through splitting of other buckets) in this round





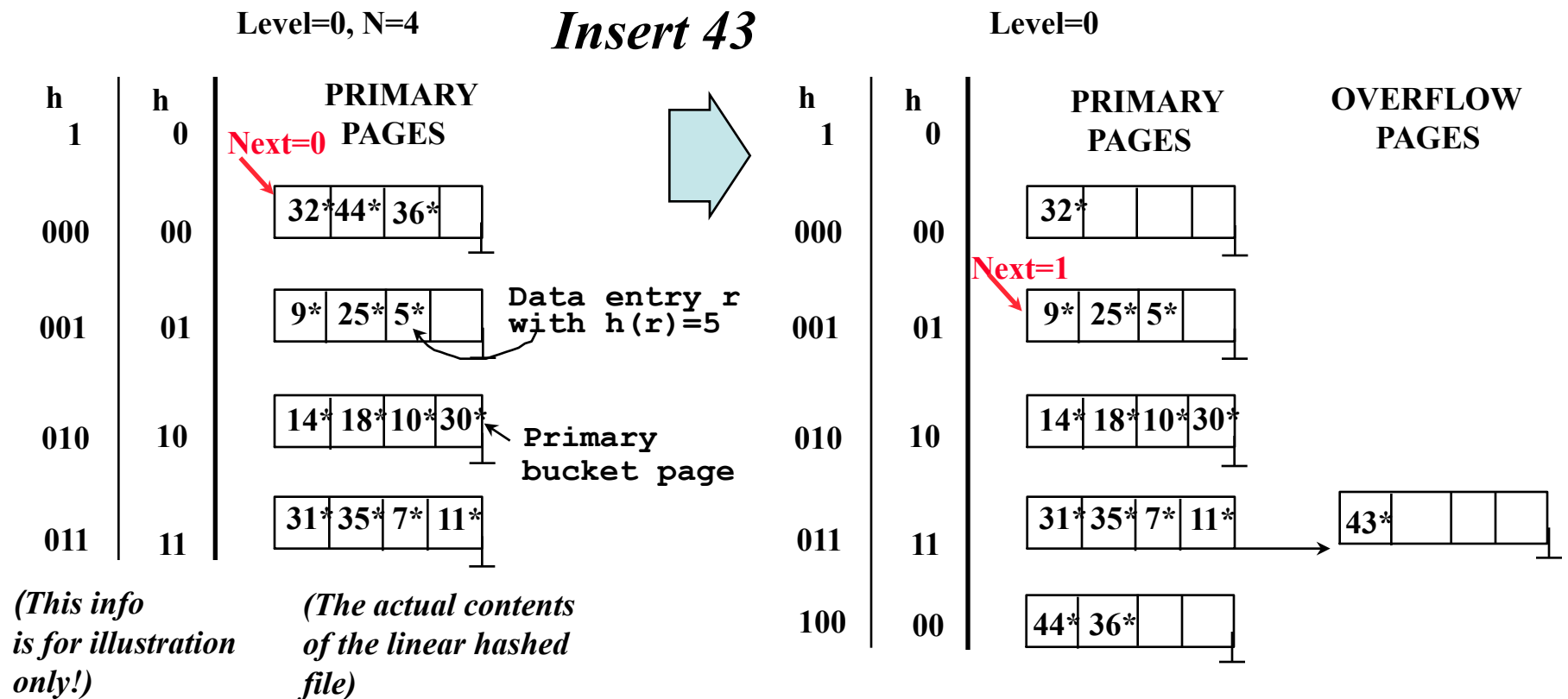
## Linear Hashing (Contd.)

- ❖ **Insert**: Find bucket by applying  $h_{Level} / h_{Level+1}$ :
  - If bucket to insert into is full:
    - Add overflow page and insert data entry.
    - Split *Next* bucket and any associated overflow pages and increment *Next*.
    - The bucket that is split may not be the same as the one that overflowed!
- ❖ Can choose alternate criterions to 'trigger' split
- ❖ *Next* must be updated sequentially. Since buckets are split round-robin, long overflow chains don't develop!
- ❖ Doubling of directory in Extendible Hashing is similar; switching of hash functions is *implicit* in how the # of bits examined is increased



# Example of Linear Hashing

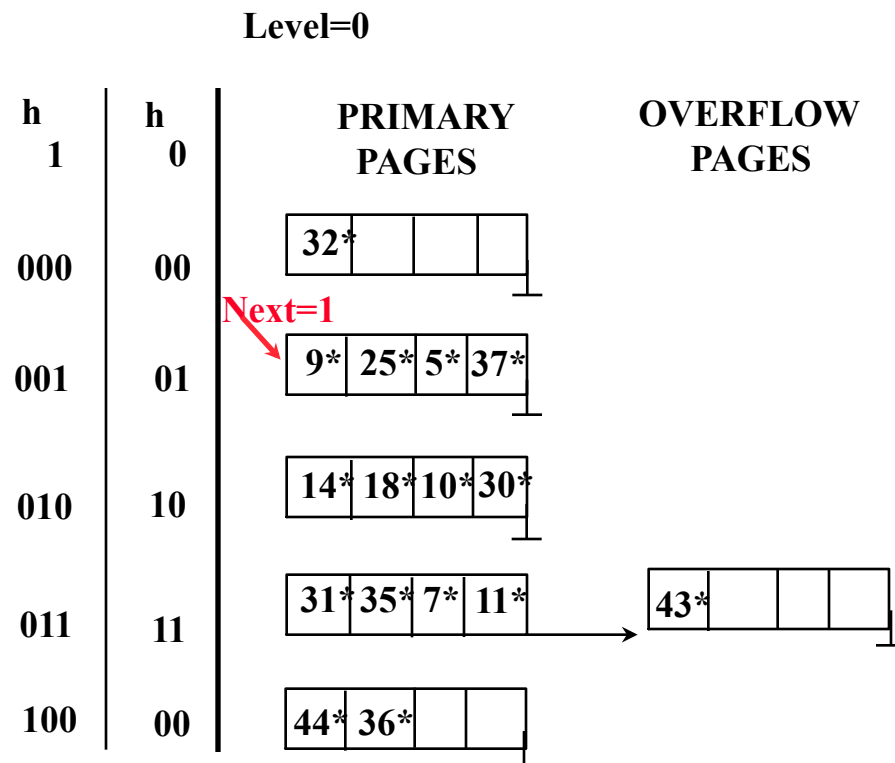
- ❖ On **split**,  $h_{Level+1}$  is used to **redistribute** entries.
- ❖ If bucket is full, Spill, Split 'Next', Move 'Next'





# Insert 37 (00100101)

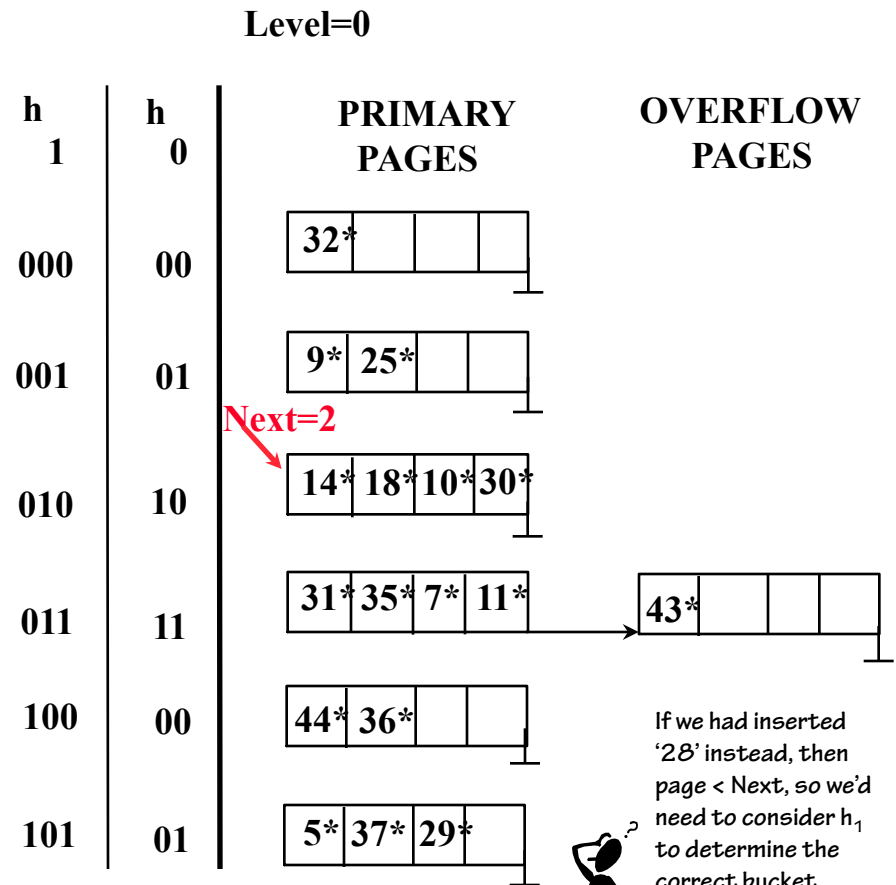
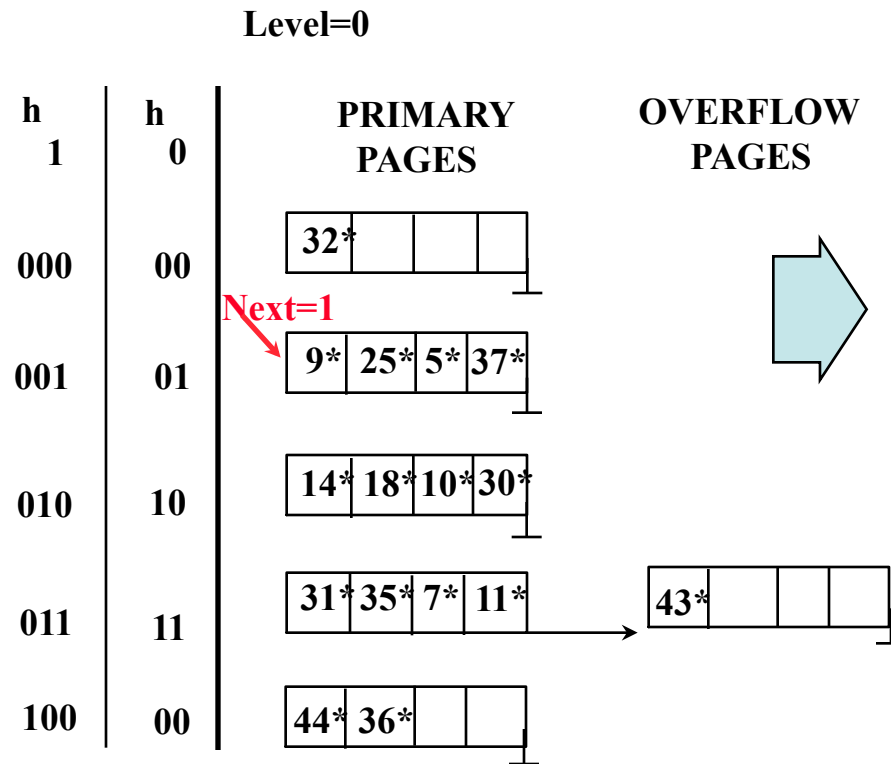
- ❖ References page  $\geq$  "Next", check  $h_0$  page, fits, no action





# Insert 29 (00011101)

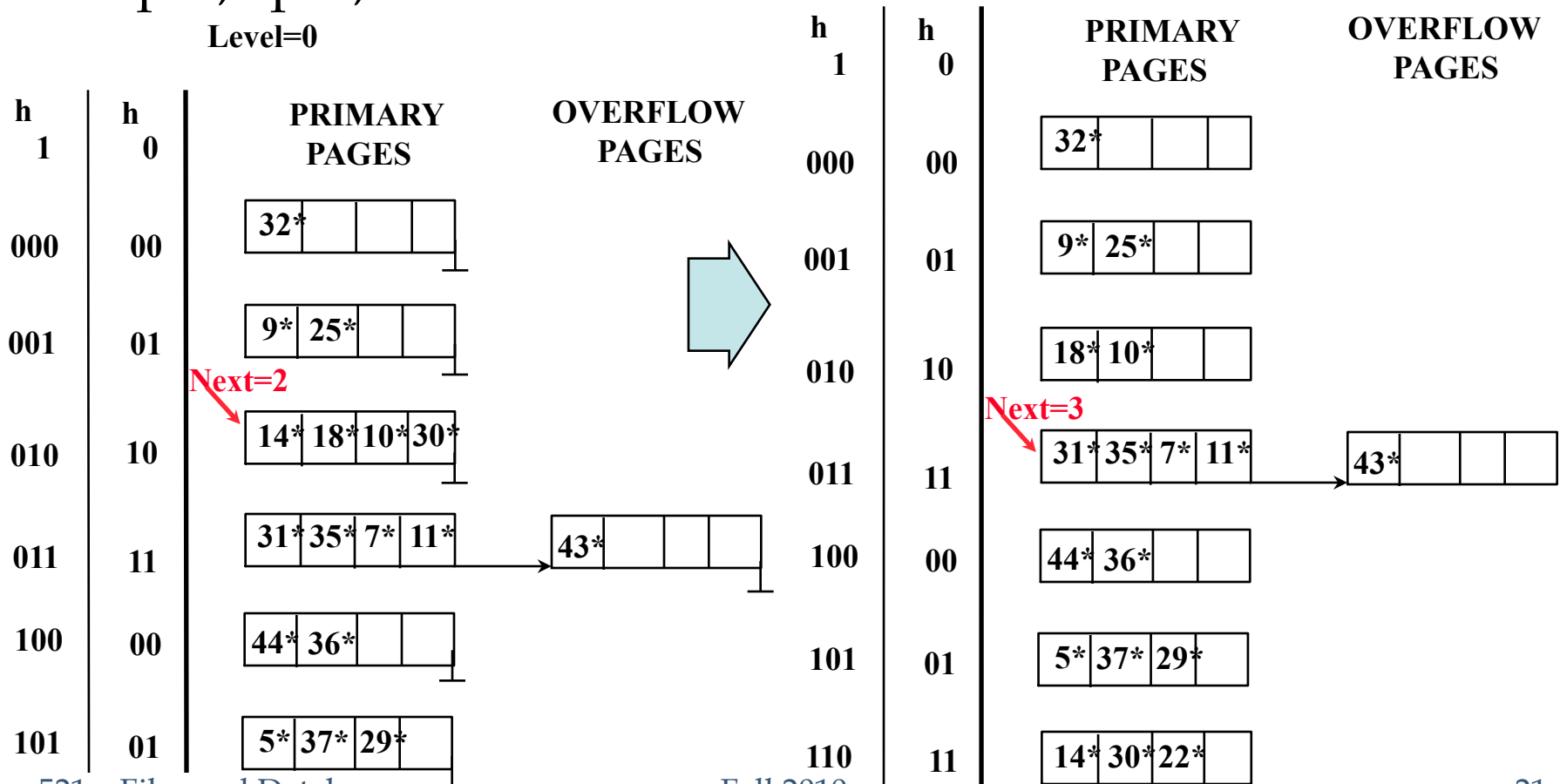
- ❖ References page  $\geq$  "Next", check  $h_0$  page
- ❖ Spill, split, move Next





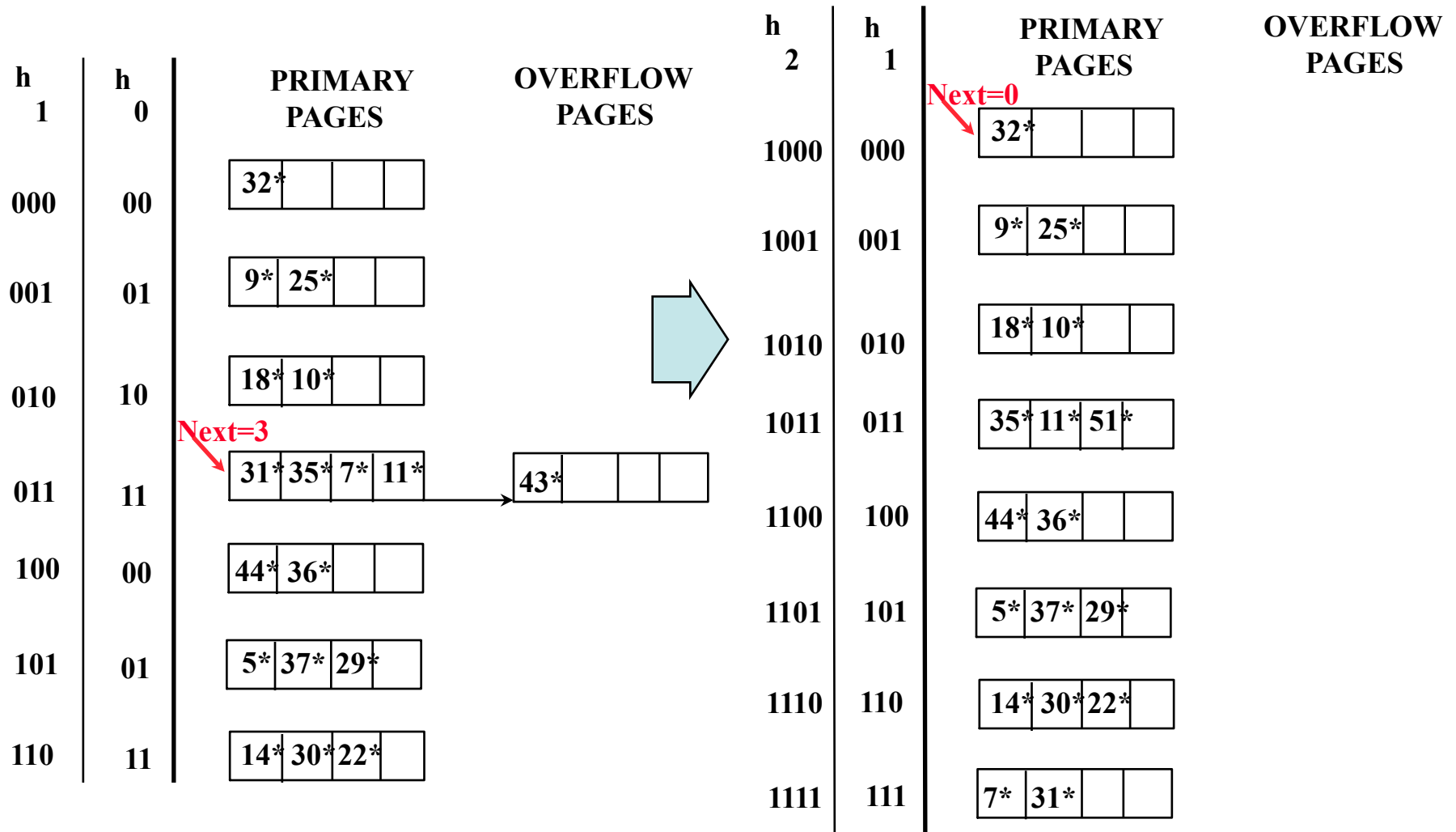
# Insert 22 (00010110)

- ❖ References page  $\geq$  "Next", check  $h_0$  page
- ❖ spill, split, move Next





# Add 51 (00110011): End of a Round





## *LH Described as a Variant of EH*

- ❖ The two schemes are actually quite similar:
  - Begin with an EH index where directory has  $N$  elements.
  - Use overflow pages, split buckets round-robin.
  - First split is at bucket 0. (Imagine directory being doubled at this point.) But elements  $\langle 1, N+1 \rangle$ ,  $\langle 2, N+2 \rangle$ , ... are the same. So, need only create directory element  $N$ , which differs from 0, now.
    - When bucket 1 splits, create directory element  $N+1$ , etc.
- ❖ So, directory can double gradually. Also, primary bucket pages are created in order. If they are *allocated* in sequence too (so that finding  $i^{\text{th}}$  is easy), we actually don't need a directory! Voila, LH.



# Summary

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- ❖ Hash-based indexes: best for equality searches, cannot support range searches.
- ❖ Static Hashing can lead to long overflow chains.
- ❖ Extendible Hashing avoids overflow pages by splitting a full bucket when a new data entry is to be added to it. (*Duplicates may require overflow pages.*)
  - Directory to keep track of buckets, doubles periodically.
  - Can get large with skewed data; additional I/O if this does not fit in main memory.





## *Summary (Contd.)*

- ❖ Linear Hashing avoids a directory by splitting buckets round-robin, and using overflow pages.
  - Overflow pages not likely to be long, nor around for long.
  - Duplicates handled easily.
  - Space utilization could be lower than Extendible Hashing, since splits not concentrated on `dense' data areas.
    - Can tune criterion for triggering splits to trade-off slightly longer chains for better space utilization.
- ❖ For hash-based indexes, a *skewed* data distribution is one in which the *hash values* of data entries are not uniformly distributed!